

1. Awarding institution	The Royal Veterinary College
2. Teaching institution	The Royal Veterinary College (University of London)
3. Programme accredited by	N/A
4. Final award	Doctorate (DAgriFood)

The Professional Doctorate in Agriculture and Food aims to offer agricultural and food industry employed professionals with the opportunity to develop their professional roles and to implement an independent programme of research within the workplace. The Professional Doctorate in Agriculture and Food programme is structured to deliver the opportunity to acquire advanced research skills and taught

profess

The course offers opportunities for candidates to achieve and demonstrate the following learning outcomes:

- Critical evaluation and dissemination of information from a variety of sources to develop understanding and make decisions

- Collaboration with experts and policy makers across a wide range of disciplines and organisations

- Designing and executing an independent research project or portfolio of research

- Effective and scientifically rigorous communication of scientific information and experimental conclusions in oral and written formats

- Managing human, financial and physical resources as appropriate to achieve project aims

- Monitoring of own learning and development to identify learning needs and to plan and manage their acquisition

- Reflective and self-critical approach to research and professional development

- Professional and intellectual skills to deliver leadership, inspiration and motivation of others

18. Programme outcomes - the programme offers opportunities for students to achieve and demonstrate the following learning outcomes, depending on their personal interests/responsibilities

19. Programme structures and requirements, levels, modules, credits and awards

The DAgriFood consists of a total of 540 credits: 360 at Level 8, Doctoral Level, with the remaining 180 at Level 7, Masters Level -

Compulsory modules (150 taught credits, Organisation-Focused Study, Research thesis)